

```
#include <stdlib.h>
#include <string.h>
#include <ctype.h>

#define MAXPAROLA 30
#define MAXRIGA 80

int main(int argc, char *argv[])
{
    int freq[MAXPAROLA]; /* vettore di contatori
delle frequenze delle lunghezze delle parole */
    char riga[MAXRIGA];
    int i, inizio, lunghezza;
    FILE *f;

    for(i=0; i<MAXPAROLA; i++)
        freq[i]=0;

    if(argc != 2)
    {
        printf(stderr, "ERRORE, serve un parametro con il nome del file\n");
        exit(1);
    }
    f = fopen(argv[1], "r");
    if(f==NULL)
    {
        printf(stderr, "ERRORE, impossibile aprire il file %s\n", argv[1]);
        exit(1);
    }

    while( fgets( riga, MAXRIGA, f ) != NULL )
```



# Threads

## Thread Essentials

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# Objectives

- ❖ Upon completion of this unit you will be able to run and control threads
  - Run and end threads
    - CreateThread, \_beginthreadex, ExitThread, TerminateThread
  - Wait for threads
    - WaitForSingleObject (WFSO), WaitForMultipleObjects (WFMO)
  - Other thread control functions
    - GetCurrentThread, GetCurrentThreadId,
    - SuspendThread, ResumeThread, etc.

## Create Thread

```
HANDLE CreateThread (  
    LPSECURITY_ATTRIBUTES lpsa,  
    DWORD dwStackSize,  
    LPTHREAD_START_ROUTINE lpStartAddr,  
    LPVOID lpThreadParm,  
    DWORD dwCreationFlags,  
    LPDWORD lpThreadId  
);
```


- ❖ This function allows you to run a thread and it specifies
  - The thread's start address within the process's code
  - A pointer to a thread argument
    - Each thread has a permanent `ThreadId` and it is usually accessed by a `HANDLE`

# Create Thread

## ❖ Return value

- The handle of the thread, if success
- A NULL handle, otherwise

```
int pthread_create ( POSIX  
    pthread_t *tid,  
    const pthread_attr_t *attr,  
    void *(*startRoutine)(void *),  
    void *arg  
);
```



```
HANDLE CreateThread ( Windows API  
    LPSECURITY_ATTRIBUTES lpsa,  
    DWORD dwStackSize,  
    LPTHREAD_START_ROUTINE lpStartAddr,  
    LPVOID lpThreadParm,  
    DWORD dwCreationFlags,  
    LPDWORD lpThreadId  
);
```

# Create Thread

## ❖ Parameters

### ➤ lpsa

- Security attributes structure
- Often equal to NULL

### ➤ dwStackSize

- Byte size for the new thread's stack
- Use zero to default to the primary thread's stack size (often 1 MB)

```
HANDLE CreateThread (  
    LPSECURITY_ATTRIBUTES lpsa,  
    DWORD dwStackSize,  
    LPTHREAD_START_ROUTINE lpStartAddr,  
    LPVOID lpThreadParm,  
    DWORD dwCreationFlags,  
    LPDWORD lpThreadId  
);
```

# Create Thread

## ➤ lpStartAddr

- Points to the **function** (within the calling process) to be executed
- The function accepts a single pointer argument and returns a 32-bit DWORD exit code

## ➤ lpThreadParm

- The pointer passed as the **thread argument**
- The thread can interpret the argument as a pointer to a structure

```
HANDLE CreateThread (  
    LPSECURITY_ATTRIBUTES lpsa,  
    DWORD dwStackSize,  
    LPTHREAD_START_ROUTINE lpStartAddr,  
    LPVOID lpThreadParm,  
    DWORD dwCreationFlags,  
    LPDWORD lpThreadId  
);
```

## Create Thread

.NET and Java separate thread creation from thread start. Pthreads does not

### ➤ dwCreationFlags

- If zero, the thread is immediately ready to run
- If **CREATE\_SUSPENDED**, the new thread will be in the suspended state, requiring a **ResumeThread** function call to move the thread to the ready state

### ➤ lpThreadId

- Points to a **DWORD** that receives the new thread's identifier
- It can be **NULL**

```
HANDLE CreateThread (  
    LPSECURITY_ATTRIBUTES lpsa,  
    DWORD dwStackSize,  
    LPTHREAD_START_ROUTINE lpStartAddr,  
    LPVOID lpThreadParm,  
    DWORD dwCreationFlags,  
    LPDWORD lpThreadId  
);
```

## Thread Function

```
DWORD WINAPI ThreadFunction (LPVOID);
```

- ❖ Prototype of the thread function
  - It receives a single argument (long pointer to void)
  - It returns a DWORD value



## Exit Thread

```
VOID ExitThread (DWORD exitCode);
```

- ❖ **ExitThread** is the preferred technique to exit a thread in C language
  - The thread's stack is deallocated on termination
  - All handles referring the thread are signaled
- ❖ A thread
  - Will remain in the system until the last handle to it is closed (using **CloseHandle**)
    - Only after Closehandle the thread will be deleted
  - Any other thread can retrieve its exit code **exitCode**
    - See **GetExitCodeThread** for details

## Exit Thread

- ❖ A common alternative for a thread to exit, is to **return** from the thread function
  - The exit code `exitCode` can be returned with `return`
- ❖ When the last thread in a process terminates, so does the process itself
- ❖ You can terminate a different thread with **TerminateThread**, but this is
  - Dangerous
    - Thread's resources may not be deallocated (e.g., handler not called)
  - Better to let the thread terminate itself

## Example

Array of handles

Parameters embedded  
into a C structure

```
HANDLE *threadH;  
thread_t *threadD;  
DWORD *threadId;
```

... Allocate thread, threadD, threadId ...

```
for (i=0; i<N; i++) {  
    threadD[i]. ... = ...;  
    threadH[i] = CreateThread (NULL, 0,  
        (LPTHREAD_START_ROUTINE) threadFunction,  
        &threadD[i], 0, &threadId[i]);  
    if (threadH[i] == NULL) {  
        ExitProcess(0);  
    }  
}
```

Run threads

It can be NULL

... Wait for threads ...

Wait for threads

```
for (i=0; i<N; i++) {  
    CloseHandle (threadH[i]);  
}
```

Close handles

# Example

```
DWORD WINAPI threadFunction (LPVOID lpParam) {  
    thread_t *data;  
  
    data = (thread_t *) lpParam;  
  
    ... Thread body ...  
  
    ExitThread (0);  
}
```

Thread function

Data type  
conversion (cast)

Can be captured by  
**GetExitCodeThread**

## Create Thread

- ❖ Nearly all programs (and thread functions) use the C library
- ❖ C and C++ make available functions
  - `_beginthreadex`
  - `_endthreadex`
- ❖ They have the same parameters as `CreateThread` and `ExitThread`
- ❖ Please remind to include
  - `#include <process.h>`

## Wait for Threads

- ❖ Functions `WaitForSingleObject` (WFSO) and `WaitForMultipleObjects` (WFMO) allow to wait for thread termination
- ❖ These functions, are general purpose
  - They wait for many different types of objects
    - Wait for one or more handles to become “signaled”
    - The handle/handles can represent processes, threads, semaphores, etc.
    - The meaning of “signaled” varies among object types
  - It is possible to specify an optional timeout period

## Wait for Threads

```
DWORD WaitForSingleObject (  
    HANDLE hObject,  
    DWORD dwTimeOut  
);
```

- ❖ Functions **WFSO** awaits for a **single** object
  - A single handle, **hObject**, to wait for
  - A timeout limit (**dwTimeOut**) to indicate the timeout in milliseconds
    - Zero means that the function returns immediately after testing the state of the specified objects
    - INFINITE indicates no timeout
      - Wait forever for an “object” to terminate

## Wait for Threads

```
DWORD WaitForMultipleObjects (  
    DWORD nCount,  
    LPHANDLE lpHandles,  
    BOOL fWaitAll,  
    DWORD dwTimeOut  
);
```

- ❖ Functions **WFMO** awaits for **multiple** objects
  - The set of handles in the array **lpHandles** of **nCount** size
  - The handles do not need to be of the same type (e.g., processes, threads, etc.)
    - The number of objects **nCount** should not exceed **MAXIMUM\_WAIT\_OBJECTS** (i.e., usually **64**)
    - If the parameter **fWaitAll** is **TRUE**, **WFMO** waits for **all** objects to be signaled rather than only **one**



# Wait for Threads

## ❖ WFSO and WFMO have the following possible return values

### ➤ `WAIT_OBJECT_0`

- For WFSO (or WFMO) the (a) single handle is signaled
- For WFMO, **all** handles are signaled when **fWaitAll** is TRUE

### ➤ `WAIT_OBJECT_0 + n` (where $0 \leq n < nCount$ )

- With WFMO it is possible to determine which handle was signaled by subtracting `WAIT_OBJECT_0` from the return value

```
DWORD WaitForSingleObject (HANDLE hObject, DWORD dwTimeout);
```

```
DWORD WaitForMultipleObjects (DWORD nCount,  
    LPHANDLE lpHandles, BOOL fWaitAll, DWORD dwTimeout);
```

# Wait for Threads

## ➤ WAIT\_TIMEOUT

- The timeout period elapsed before the wait could be satisfied by a signal

## ➤ WAIT\_FAILED

- The call to WFSO or WFMO failed

## ➤ WAIT\_ABANDONED\_0

- Not possible with processes or threads, used for mutex handles

```
DWORD WaitForSingleObject (HANDLE hObject,  
    DWORD dwTimeOut);
```

```
DWORD WaitForMultipleObjects (DWORD cObjects,  
    LPHANDLE lphObjects, BOOL fWaitAll, DWORD dwTimeOut);
```

# Example

Wait for threads  
one at a time

```
for (i=0; i<N; i++) {  
    WaitForSingleObject (threadH[i], INFINITE);  
    CloseHandle (threadH[i]);  
}
```

Forcing an order in the waiting  
process may be inefficient

Wait for threads  
all together

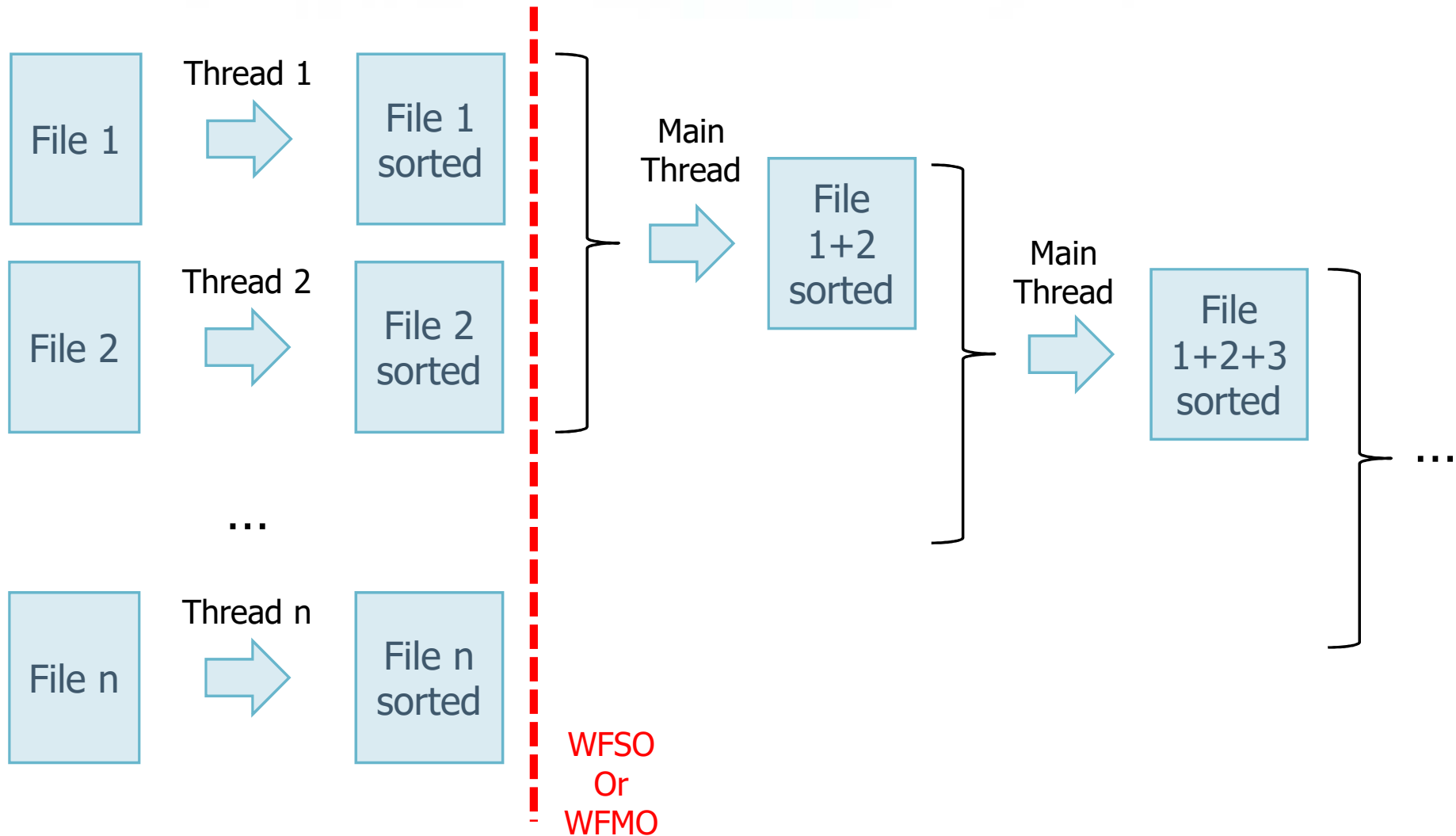
```
WaitForMultipleObjects (N, threadH, TRUE, INFINITE);  
for (i=0; i<N; i++) {  
    CloseHandle (threadH[i]);  
}
```

Can wait for at most  
**MAXIMUM\_WAIT\_OBJECTS**  
object

Laboratory 04  
Exercise 01

# Example

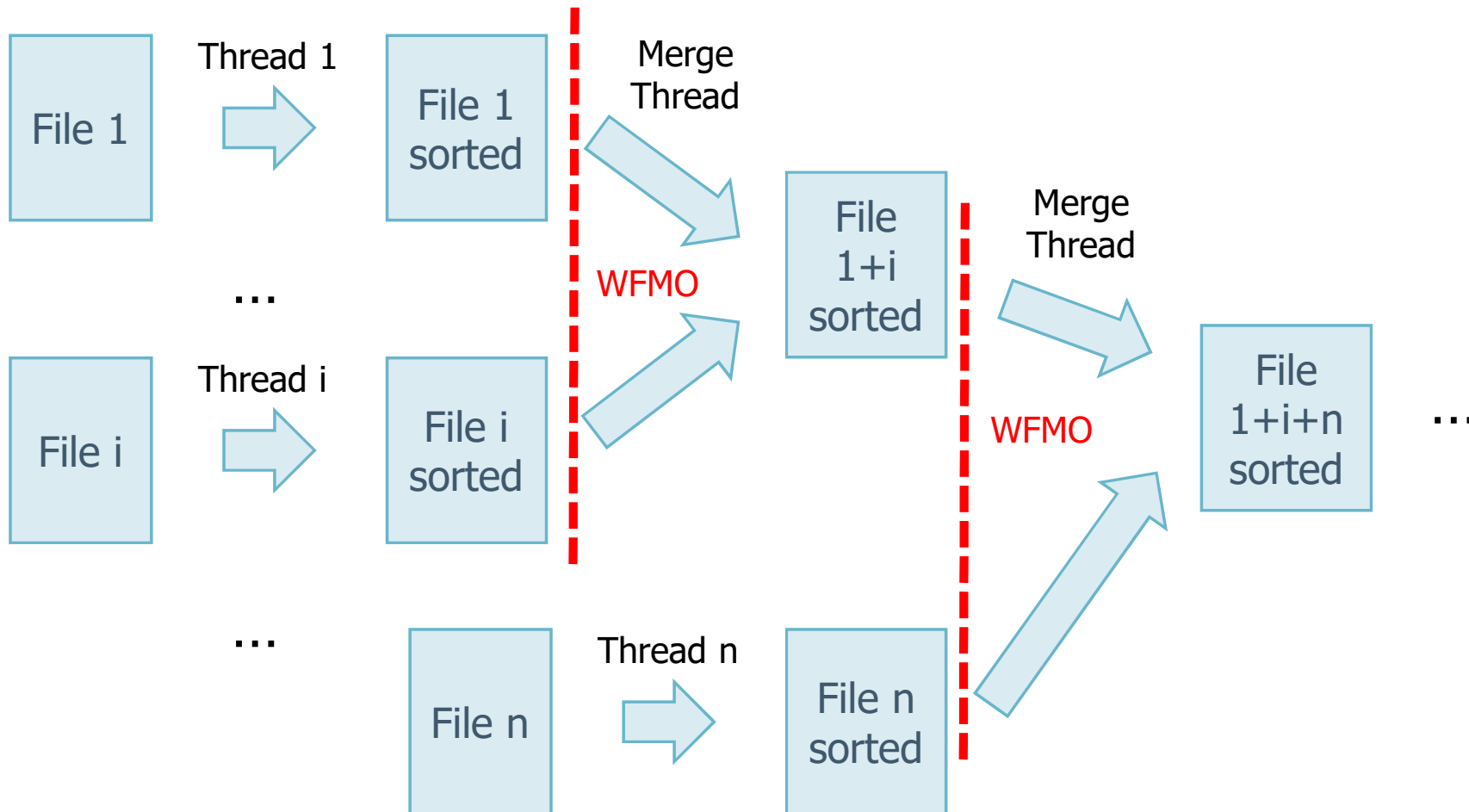
## ❖ File sorting (through sort and merge)



Laboratory 04  
Exercise 02

# Example

## ❖ File sorting (through sort and merge)



## Example

- ❖ How can we use WFMO to
  - Wait for more than **MAXIMUM\_WAIT\_OBJECTS** handles?
  - Wait (and act) for a single thread within a large group of threads

# Example

Wait for all threads in a group,  
then move into the next group

```
WaitForMultipleObjects (N, threadH, TRUE, INFINITE);
```

Wait for a large  
number of threads



Usually 64

```
for (i=0; i<N; i+=MAXIMUM_WAIT_OBJECTS) {
  WaitForMultipleObjects (
    min (MAXIMUM_WAIT_OBJECTS, N-i),
    &threadH[i], TRUE, INFINITE);
}
```

Reaming  
Threads

Wait for all  
(within the same group)  
Then move to the next group

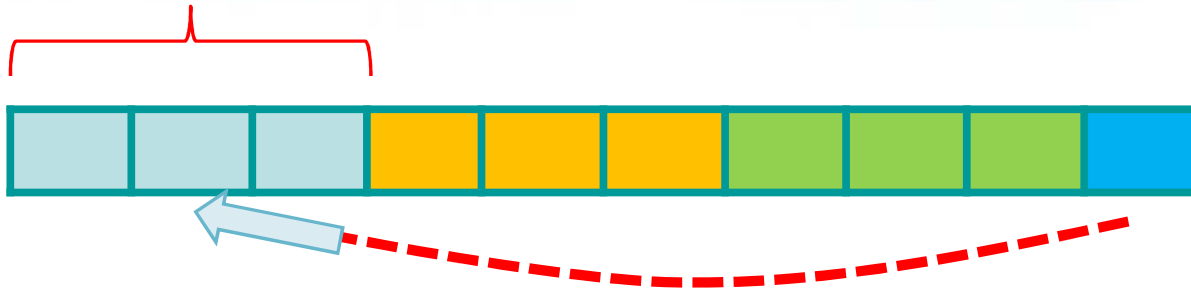
MAXIMUM\_WAIT\_OBJECTS



# Example

Wait for a single thread within the first group, then re-arrange the groups

MAXIMUM\_WAIT\_OBJECTS



```
while (N > 0) {  
    INDEX = WaitForMultipleObjects (  
        min (MAXIMUM_WAIT_OBJECTS, N),  
        threadH, FALSE, INFINITE);  
    index = (int) INDEX - (int) WAIT_OBJECT_0;  
    CloseHandle (threadH[index]);  
    ...  
    threadH[index] = threadH[N-1];  
    ... Free threadData[index] ...  
    threadData[index] = threadData[N-1];  
    N--;  
}
```

Wait for a  
single thread

Re-arrange groups  
(handles and data)



## Thread Identifiers

```
BOOL GetExitCodeThread (  
    HANDLE lThread,  
    LPDWORD lpExitCode  
);
```

- ❖ A terminated thread will exist until the last handle to it is closed (by Closehandle)
- ❖ Any other thread can retrieve its exit code
  - The code will be returned into **lpExitCode**
  - The value **STILL\_ACTIVE** will be returned if the thread is still running

## Thread Identifiers

```
HANDLE GetCurrentThread (VOID);
```

```
DWORD GetCurrentThreadId (VOID);
```

```
DWORD GetThreadId (HANDLE threadHandle);
```

- ❖ These functions are used to obtain
  - GetCurrentThread the thread handle
  - GetCurrentThreadId the thread identifier
  - GetThreadId the thread's ID from its handle

## Resume & Suspend Threads

```
DWORD ResumeThread (HANDLE hThread);
```

```
DWORD SuspendThread (HANDLE hThread);
```

- ❖ Every thread has a suspend count
  - A thread can execute only if this count is zero
- ❖ A thread can be created in the suspended state
- ❖ One thread can
  - Increment the suspend count of another thread (resume)
  - Decrement the suspend count of another thread (suspend)

## Resume & Suspend Threads

- ❖ Return value
  - Both functions return previous suspend count
  - The value 0xFFFFFFFF, in case of failure
- ❖ Useful in preventing “race conditions”
  - Do not allow threads to start until initialization is complete
- ❖ Unsafe for general synchronization

## Thread's Priority

```
DWORD SetThreadPriority (  
    HANDLE hThread, DWORD dwPriority);  
  
DWORD GetThreadPriority (HANDLE hThread);
```

- ❖ Change or determine a thread's priority
  - For itself
  - For another process, security permitting
- ❖ Thread priorities are relative to the process base priority (the priority class)
  - See **SetPriorityClass** and **GetPriorityClass** for further details

# Thread's Priority

- Use constant values as **dwPriority**
  - `THREAD_PRIORITY_LOWEST`,  
`THREAD_PRIORITY_BELOW_NORMAL`, etc.
- ❖ Modify the priority with cautions
  - Use high thread priorities with caution
  - Avoid real time priorities for user processes
    - User threads may preempt executive threads
  - Assure fairness
    - All threads should run eventually
    - Real time priorities may prevent fairness
      - "Priority inversion"
      - "Thread starvation"