

Heap Sort

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ADT Heap

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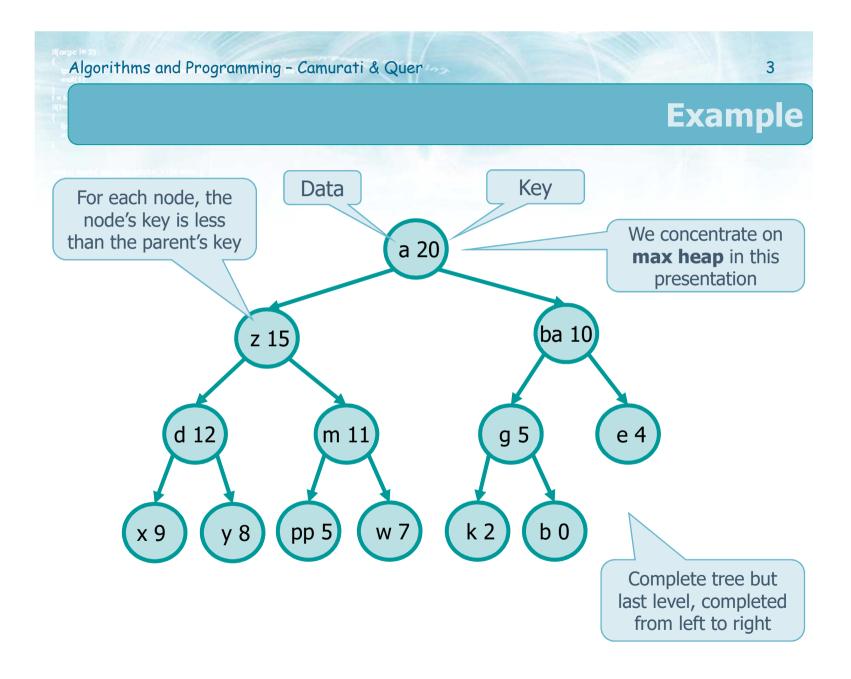
A heap is a binary tree with

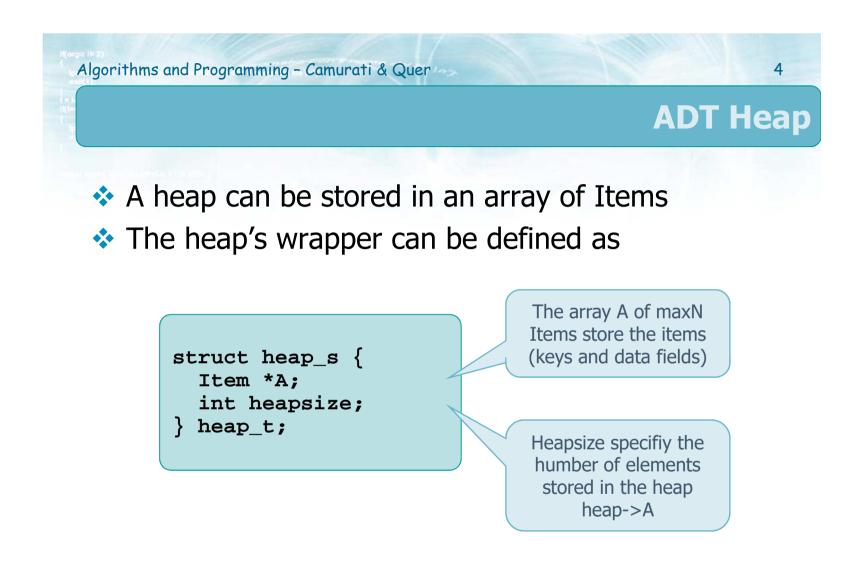
- > A structural property
 - Almost complete and almost balanced
 - All levels are complete, possibly except the last one, filled from left to right

We have both **max** and **min** heaps

> A functional property (max heap)

- For each node different from the root we have that the key of the node is less than the key of the parent node
 - key[parent(node)] ≥ key(node)
- Consequence
 - > The maximum key is in the root

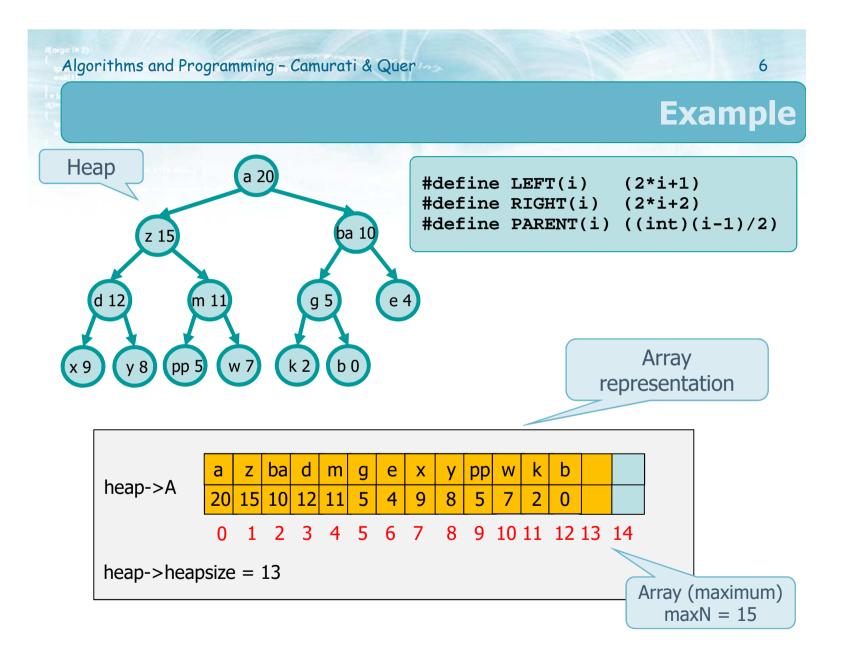


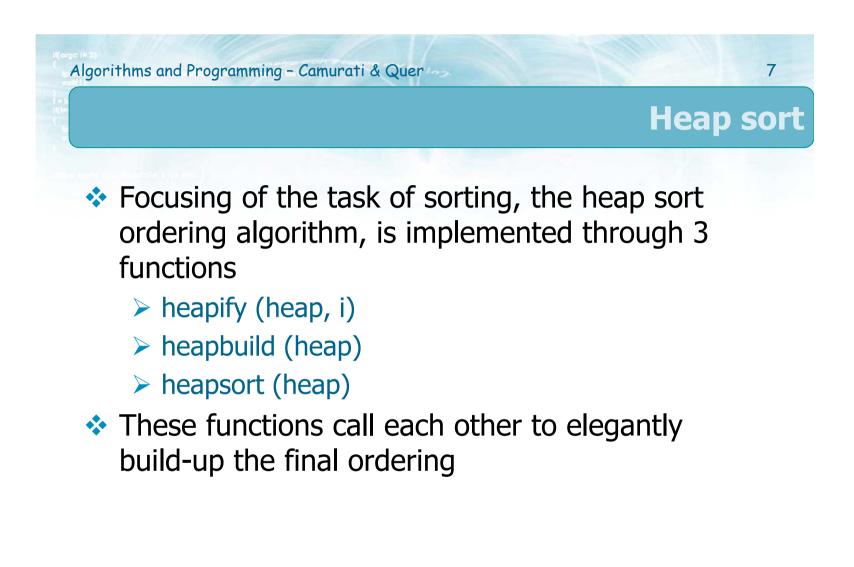


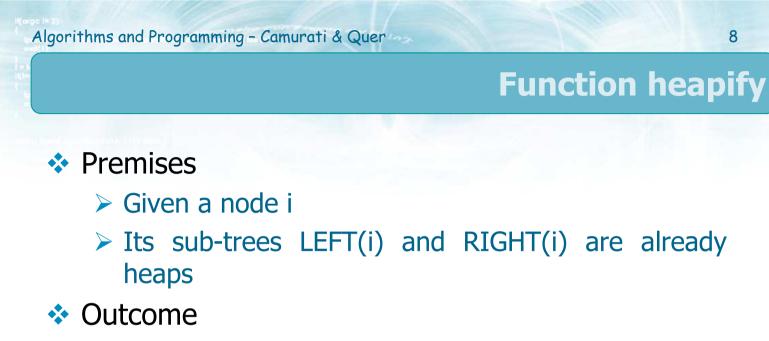




- The root of the heap is stored in
 - heap->A[0]
- Given a node i, we define
 - LEFT(i) = 2'i+1
 - ➤ RIGHT(i) = 2'i+2
 - PARENT(i)=(i-1)/2
- Thus given a node heap->A[i]
 - Its left child is heap->A[LEFT(i)]
 - Its right child is heap->A[RIGHT(i)]
 - Its parent is heap->A[PARENT(i)]







Turn into a heap the entire tree rooted at i, i.e., node i, with sub-trees LEFT(i) and RIGHT(i)

Function heapify

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Process

- Compare A[i], LEFT(i) and RIGHT(i)
 - Assign to A[i] the maximum among A[i], LEFT(i) and RIGHT(i)

If there has been a swap between A[i] and LEFT(i)

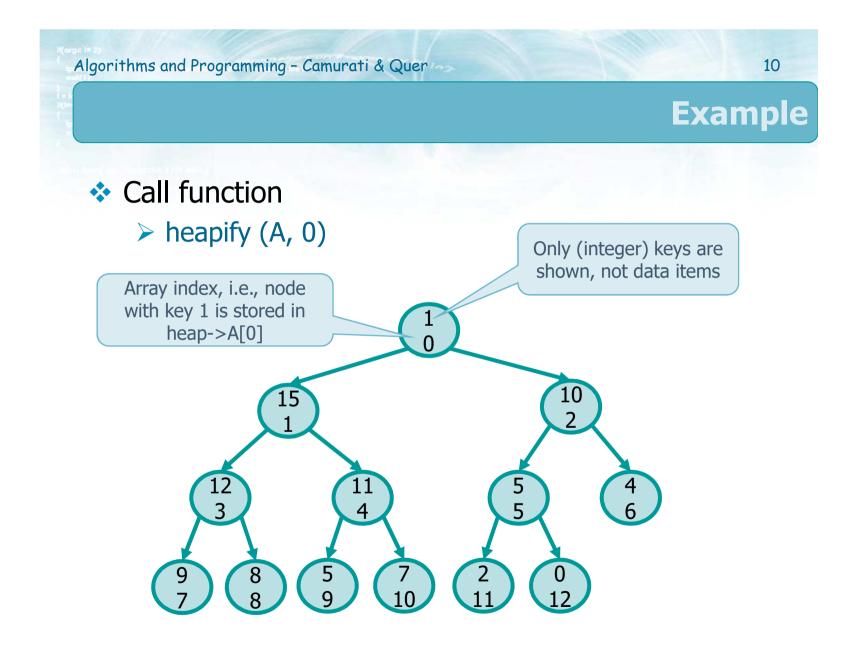
 Recursively apply heapify on the subtree whose root is LEFT(i)

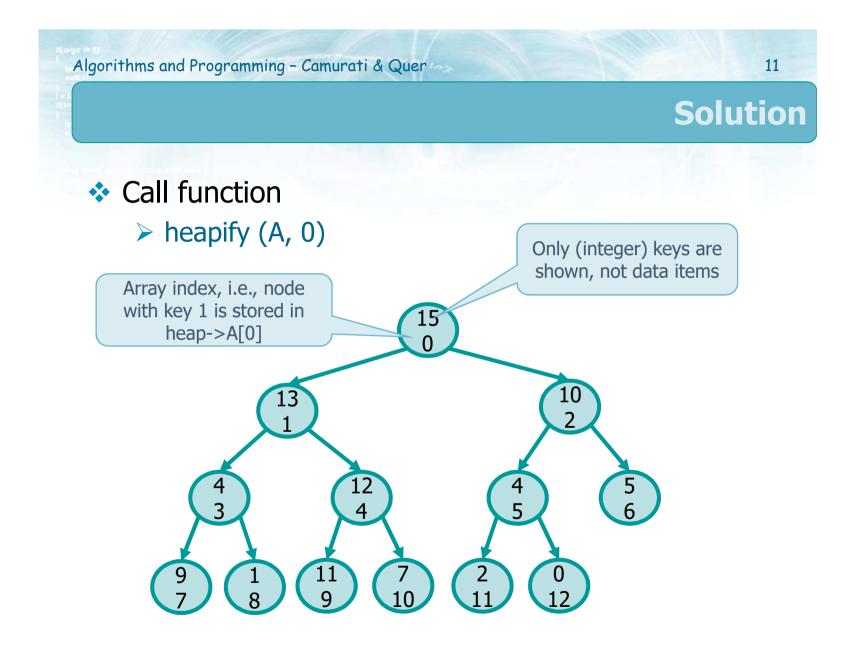
> If there has been a swap between A[i] and RIGHT(i)

- Recursively apply heapify on the subtree whose root is RIGHT(i)
- Complexity

 \succ T(n) = O(lg n)

Height of the node log n for the entire tree

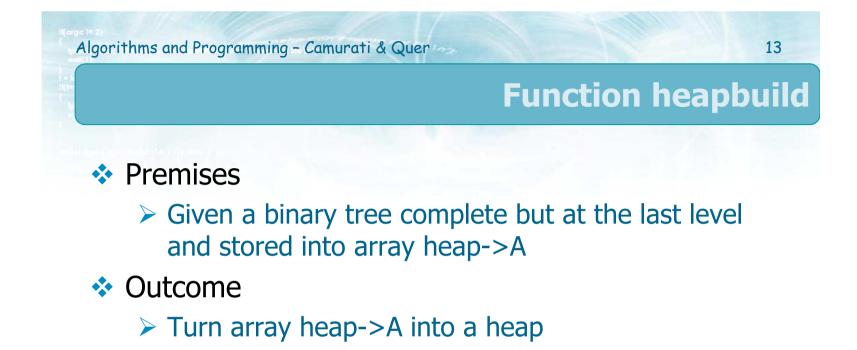




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Implementation

```
void heapify (heap_t heap, int i) {
                                                 Function
  int l, r, largest;
                                               item greater
  l = LEFT(i);
                                               compares keys
  r = RIGHT(i);
  if ((l<heap->heapsize) &&
      (item greater (heap->A[1], heap->A[i])))
    largest = 1;
  else
    largest = i;
  if ((r<heap->heapsize)&&
      (item greater (heap->A[r], heap->A[largest])))
    largest = r;
  if (largest != i) {
    swap (heap, i, largest);
    heapify (heap, largest);
  return;
}
```



Function heapbuild

Process

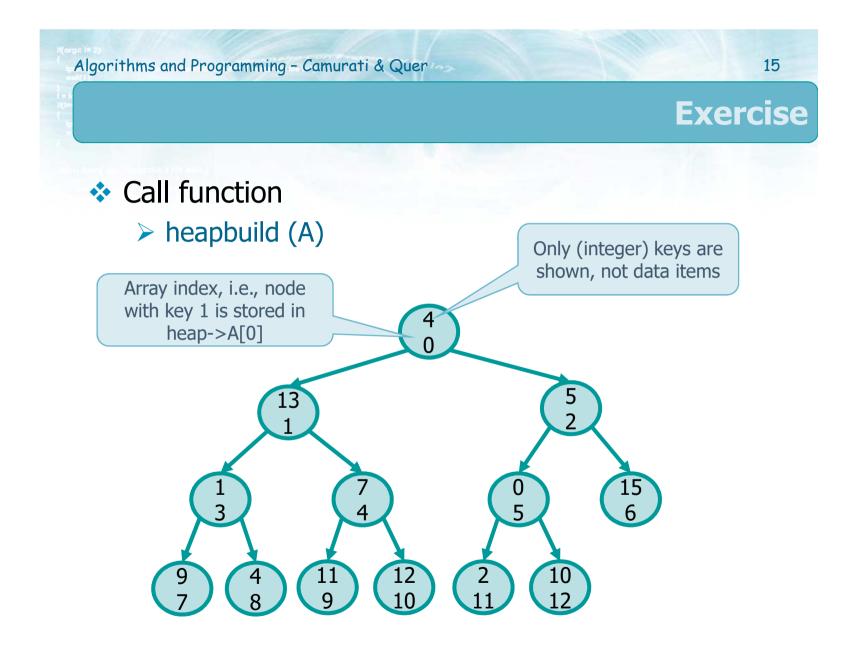
Leaves are heaps

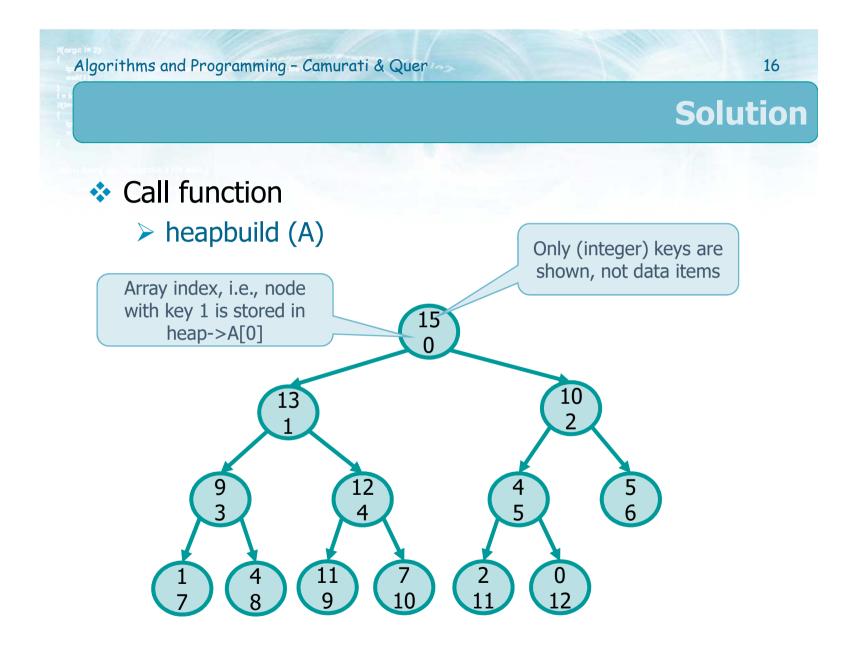
Apply the **heapify** function

- Starting from the parent node of the last pair of leaves
- Move backward on the array until the root is manipulated
- Complexity

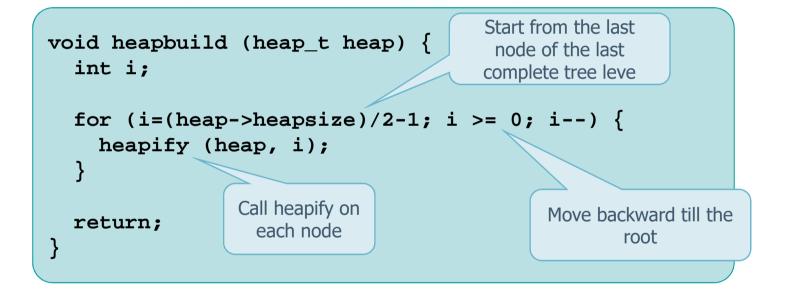
➤ T(n)= O(n)

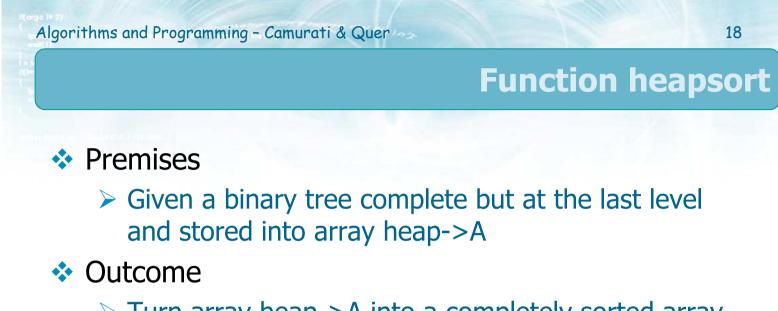
N calls to heapify should imply O(n·log). This bound is correct but not tight. A tighter bound can be proven by a more accurate count of the height of the subtrees and the number of calls to heapify.





Implementation





> Turn array heap->A into a completely sorted array

Function heapsort

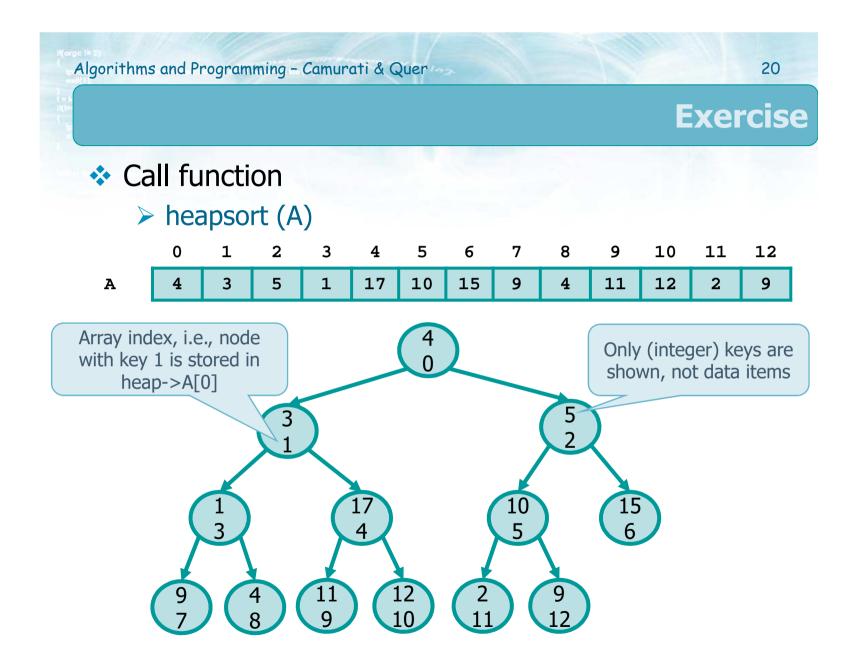
Process

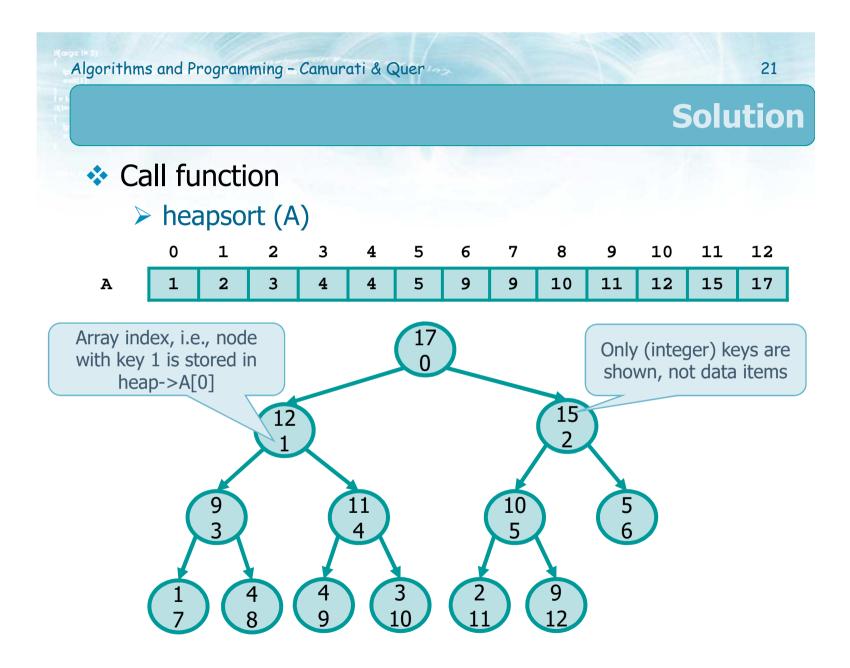
- > Turns the array into a heap using **heapbuild**
- Swaps first and last elements
- Decreases heap size by 1
- Reinforces the heap property using heapify
- Repeats until the heap is empty and the array ordered
- Complexity

➤ T(n)= O (n · lg n)

- In place
- Not stable

A single call to buildheap \rightarrow O(n) + n calls to heapify, each one \rightarrow O(log n) = implies an overall cost \rightarrow O(n·logn)





Implementation

